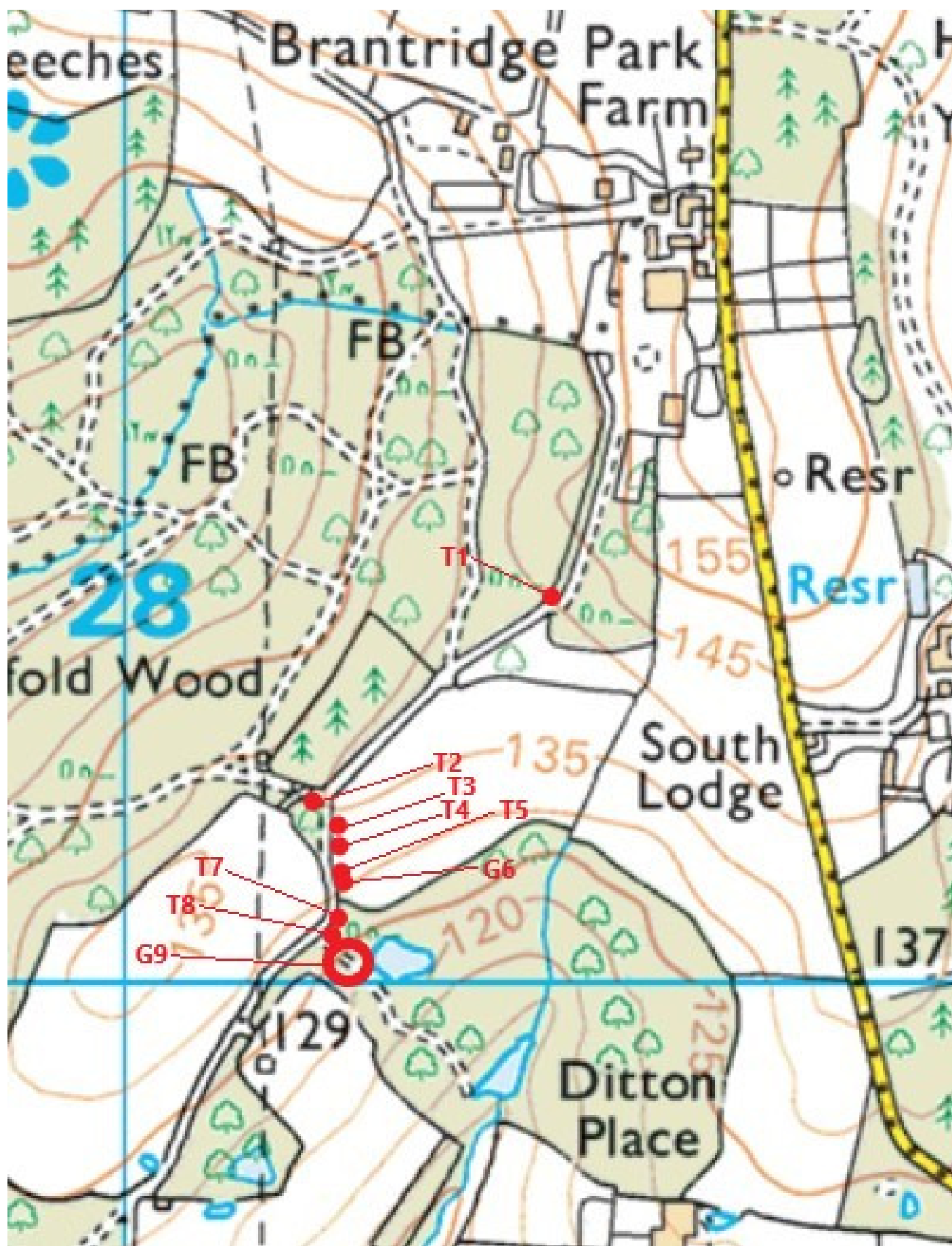


Plan 1 – trees on access road



Plan 2 – trees near pods

